

$$1 \quad \begin{bmatrix} 2 & 4 & 6 & 4 & \mathbf{b}_1 \\ 2 & 5 & 7 & 6 & \mathbf{b}_2 \\ 2 & 3 & 5 & 2 & \mathbf{b}_3 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 & \mathbf{b}_1 \\ 0 & 1 & 1 & 2 & \mathbf{b}_2 - \mathbf{b}_1 \\ 0 & -1 & -1 & -2 & \mathbf{b}_3 - \mathbf{b}_1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 & \mathbf{b}_1 \\ 0 & 1 & 1 & 2 & \mathbf{b}_2 - \mathbf{b}_1 \\ 0 & 0 & 0 & 0 & \mathbf{b}_3 + \mathbf{b}_2 - 2\mathbf{b}_1 \end{bmatrix}$$

$A\mathbf{x} = \mathbf{b}$ has a solution when $b_3 + b_2 - 2b_1 = 0$; the column space contains all combinations of $(2, 2, 2)$ and $(4, 5, 3)$. **This is the plane** $b_3 + b_2 - 2b_1 = 0$ (!). The nullspace contains all combinations of $\mathbf{s}_1 = (-1, -1, 1, 0)$ and $\mathbf{s}_2 = (2, -2, 0, 1)$; $\mathbf{x}_{complete} = \mathbf{x}_p + c_1\mathbf{s}_1 + c_2\mathbf{s}_2$;

$$\begin{bmatrix} R & \mathbf{d} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & -2 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \text{ gives the particular solution } \mathbf{x}_p = (4, -1, 0, 0).$$

$$3 \quad \mathbf{x}_{complete} = \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix}. \text{ The matrix is singular but the equations are}$$

still solvable; \mathbf{b} is in the column space. Our particular solution has free variable $y = 0$.

$$4 \quad \mathbf{x}_{complete} = \mathbf{x}_p + \mathbf{x}_n = \left(\frac{1}{2}, 0, \frac{1}{2}, 0\right) + x_2(-3, 1, 0, 0) + x_4(0, 0, -2, 1).$$

8 (a) Every \mathbf{b} is in $C(A)$: *independent rows*, only the zero combination gives $\mathbf{0}$.

(b) We need $b_3 = 2b_2$, because $(\text{row } 3) - 2(\text{row } 2) = \mathbf{0}$.

$$10 \quad \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 2 \\ 4 \end{bmatrix} \text{ has } \mathbf{x}_p = (2, 4, 0) \text{ and } \mathbf{x}_{null} = (c, c, c). \text{ Many possible } A!$$

11 A 1 by 3 system has at least **two** free variables. But \mathbf{x}_{null} in Problem 10 only has **one**.

12 (a) If $A\mathbf{x}_1 = \mathbf{b}$ and $A\mathbf{x}_2 = \mathbf{b}$ then $\mathbf{x}_1 - \mathbf{x}_2$ and also $\mathbf{x} = \mathbf{0}$ solve $A\mathbf{x} = \mathbf{0}$

$$(b) A(2\mathbf{x}_1 - 2\mathbf{x}_2) = \mathbf{0}, A(2\mathbf{x}_1 - \mathbf{x}_2) = \mathbf{b}$$

16 The largest rank is 3. Then there is a pivot in every *row*. The solution *always exists*. The column space is \mathbf{R}^3 . An example is $A = [I \ F]$ for any 3 by 2 matrix F .

17 The largest rank of a 6 by 4 matrix is 4. Then there is a pivot in every *column*. The solution is *unique* (if there is a solution). The nullspace contains only the *zero vector*. An example is $A = R = [I \ F]$ for any 4 by 2 matrix F .

22 If $Ax_1 = b$ and also $Ax_2 = b$ then $A(x_1 - x_2) = 0$ and we can add $x_1 - x_2$ to any solution of $Ax = B$: the solution x is not unique. But there will be **no solution** to $Ax = B$ if B is not in the column space.

31 For $A = \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 0 & 3 \end{bmatrix}$, the only solution to $Ax = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is $x = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. B cannot exist since 2 equations in 3 unknowns cannot have a unique solution.

34 (a) If $s = (2, 3, 1, 0)$ is the only special solution to $Ax = 0$, the complete solution is $x = cs$ (a line of solutions). The rank of A must be $4 - 1 = 3$.

(b) The fourth variable x_4 is *not free* in s , and R must be $\begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$.

(c) $Ax = b$ can be solved for all b , because A and R have *full row rank* $r = 3$.

36 If $Ax = b$ and $Cx = b$ have the same solutions, A and C have the same shape and the same nullspace (take $b = 0$). If $b =$ column 1 of A , $x = (1, 0, \dots, 0)$ solves $Ax = b$ so it solves $Cx = b$. Then A and C share column 1. Other columns too: $A = C$!